#### Sensing Device

## 3 Axis Acceleration Sensor

# M-A370AD10

- Ultra-low noise, surpassing USGS New High Noise Model  $^{[1]}$  0.02  $\mu G/\sqrt{Hz}$  typ. (1 Hz ~ 10 Hz)
- High-precision Amplitude Response :  $\pm 0.4$  dB, Phase Response :  $\pm 0.1$  °, Sensitivity Error :  $\pm 500 \times 10^{-6}$
- High dynamic range  $\pm$  10 G (170 dB)
- High bias stability Temperature Error : ± 0.5 mG Max., Bias Repeatability for 1 year : ± 0.1 mG Typ.
- GNSS synchronization by 1 PPS (Pulse Per Second)
- 3-axis digital output SPI / UART that is not easily affected by noise

#### **Recommended Application**

- Seismic measurement 
  Resource exploration 
  Tilt measurement
- Structural Health Monitoring (SHM) 
  Vibration analysis / control / stabilization

[1] Peterson, J., "Observations and Modeling of Seismic Background Noise", USGS Open-File Report 93-322, 1993

#### Recommended Operating Condition

Parameter	Conditions	Min.	Тур.	Max.	Unit
V <sub>cc</sub> to GND		3.15	3.3	3.45	V
Digital input voltage to GND		GND		V <sub>cc</sub>	V
Digital output voltage to GND		- 0.3		V <sub>CC</sub> + 0.3	V
Operating temperature range		- 30		+ 85	°C
Startup time	Power-on to start output.			900	ms

#### Specifications

$T_A = -30$ °C to + 85 °C, $V_{CC} = 3.15$ V to 3	45 V < + 1 G unless otherwise	e noted			
	itions / Comments	Min.	Тур.	Max.	Unit
ACCELERATION			.,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,		
Sensitivity					
Output Range f = DC ~ 2	10 Hz	- 10		+ 10	G
Scale Factor 2 <sup>-24</sup> G/LSE			0.06		µG/LSB
Sensitivity Error 25 °C, -1 0	G~1G		± 500		x10 <sup>-6</sup>
Nonlinearity 25 °C, -1 (	G ~ 1 G, Best fit straight line			± 0.03	%
Cross Axis Sensitivity No alignm	ent correction		± 0.2		%
Bias					
Initial Error 25°C				± 2.0	mG
Bias Repeatability <sup>*4</sup> One year V <sub>cc</sub> = 3.3	after <mark>shipme</mark> nt, 25 °C, V, Aver <mark>age</mark>		± 0.1		mG
Bias Temperatu <mark>re</mark> Error Bias offse	change from 25°C reference			± 0.5	mG
Temperature se <mark>ns</mark> itivity			± 0.1		mG/°C
Noise					
Noise Density 25 °C, Ave	erage, f = 1 Hz ~ 10 Hz		0.02	0.04	µG/√Hz, rms
Cantilever Resonance Frequency <sup>*1</sup> 25 °C, V <sub>cc</sub>	= 3.3 V		450		Hz
FUNCTION					
Built-in LPF cut off -6 dB at +:	25 °C, selectable	9		210	Hz
User LPF			4, 64, 128, 512 Tap		Тар
Output data rate User select	table	50		1,000	Hz
1 PPS Input Cycle		1 - 10 <sup>-5</sup>	1	1 + 10 <sup>-5</sup>	s
Ext.trigger jitter ADC's com	bletion to Ext.trigger input	0		5	μs
TEMPERATURE SENSOR				•	
Output Range		- 30		+ 85	°C
16-bit Scale Factor <sup>*2</sup> Output = 2	:634 (0x0A4A) at 25 °C		- 0.0037918		°C/LSB
RELIABILITY				1	
MTTF <sup>*3</sup> 25 °C		87,600			h

\*1) Please make sure that a vibration on this product around the resonance frequency does not exceed 5 mG. Please take an appropriate action (e.g. installing a damper mechanism) if it exceeds 5 mG.

\*2) This is a reference value used for the internal temperature correction, and is not guaranteed to accurately output the interior temperature.

\*3) Based on the test results, the estimated value is determined under the condition of an 80 % reliability level.

\*4) Estimated value from accelerated testing results.

Note) The values in the specifications are based on the data calibrated at the factory. The values may change according to the way the product is used.

Note) The Max/Min value is the maximum/minimum value of the design or factory shipment examination, unless otherwise specified.

Note) The calibrated standard 1 G gravitational acceleration value is 9.80665 m/s<sup>2</sup>.

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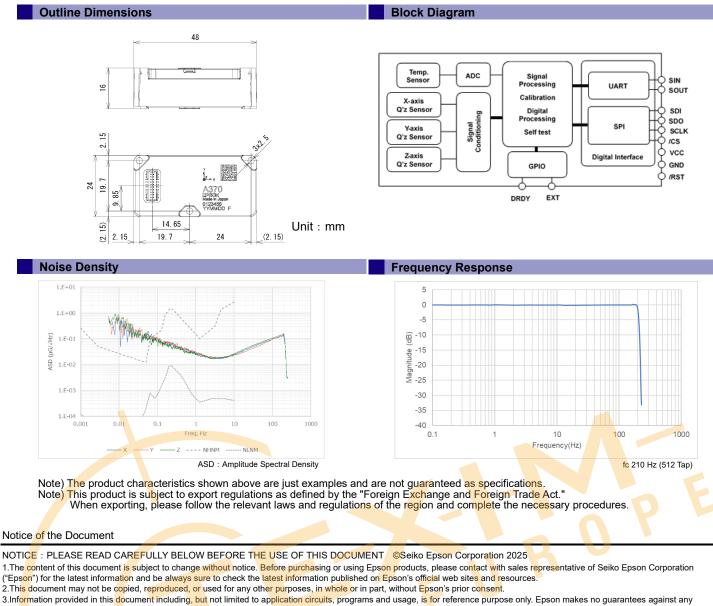
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Sensor



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