

# BOXER-8221AI

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Compact Fanless Embedded AI@Edge Box PC  
with NVIDIA® Jetson Nano™  
User's Manual 5<sup>th</sup> Ed

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## Packing List

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Before setting up your product, please make sure the following items have been shipped:

Item	Quantity
● BOXER-8221AI	1
● Wall mount bracket	2
● Power Connector	1

If any of these items are missing or damaged, please contact your distributor or sales representative immediately.



## About this Document

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This User's Manual contains all the essential information, such as detailed descriptions and explanations on the product's hardware and software features (if any), its specifications, dimensions, jumper/connector settings/definitions, and driver installation instructions (if any), to facilitate users in setting up their product.

Users may refer to the product page at [AAEON.com](http://AAEON.com) for the latest version of this document.



## Safety Precautions

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Please read the following safety instructions carefully. It is advised that you keep this manual for future references

1. All cautions and warnings on the device should be noted.
2. All cables and adapters supplied by AAEON are certified and in accordance with the material safety laws and regulations of the country of sale. Do not use any cables or adapters not supplied by AAEON to prevent system malfunction or fires.
3. Make sure the power source matches the power rating of the device.
4. Position the power cord so that people cannot step on it. Do not place anything over the power cord.
5. Always completely disconnect the power before working on the system's hardware.
6. No connections should be made when the system is powered as a sudden rush of power may damage sensitive electronic components.
7. If the device is not to be used for a long time, disconnect it from the power supply to avoid damage by transient over-voltage.
8. Always disconnect this device from any AC supply before cleaning.
9. While cleaning, use a damp cloth instead of liquid or spray detergents.
10. Make sure the device is installed near a power outlet and is easily accessible.
11. Keep this device away from humidity.
12. Place the device on a solid surface during installation to prevent falls
13. Do not cover the openings on the device to ensure optimal heat dissipation.
14. Watch out for high temperatures when the system is running.
15. Do not touch the heat sink or heat spreader when the system is running
16. Never pour any liquid into the openings. This could cause fire or electric shock.

17. As most electronic components are sensitive to static electrical charge, be sure to ground yourself to prevent static charge when installing the internal components. Use a grounding wrist strap and contain all electronic components in any static-shielded containers.
18. If any of the following situations arises, please contact our service personnel:
  - i. Damaged power cord or plug
  - ii. Liquid intrusion to the device
  - iii. Exposure to moisture
  - iv. Device is not working as expected or in a manner as described in this manual
  - v. The device is dropped or damaged
  - vi. Any obvious signs of damage displayed on the device
19. **DO NOT LEAVE THIS DEVICE IN AN UNCONTROLLED ENVIRONMENT WITH TEMPERATURES BEYOND THE DEVICE'S PERMITTED STORAGE TEMPERATURES (SEE CHAPTER 1) TO PREVENT DAMAGE.**

## FCC Statement

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### **Warning!**



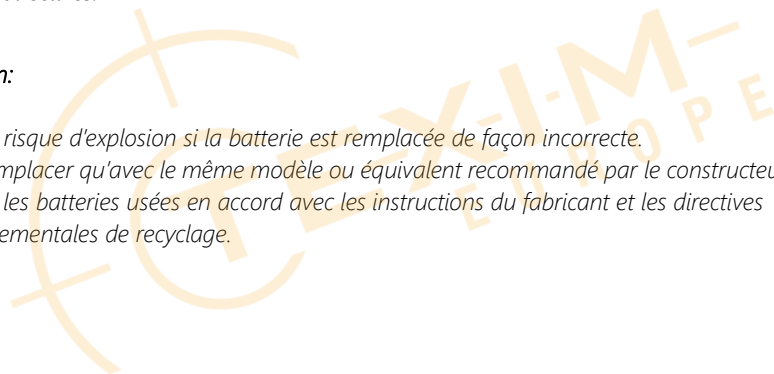
This device complies with Part 15 FCC Rules. Operation is subject to the following two conditions: (1) this device may not cause harmful interference, and (2) this device must accept any interference received including interference that may cause undesired operation.

### **Caution:**

*There is a danger of explosion if the battery is incorrectly replaced. Replace only with the same or equivalent type recommended by the manufacturer. Dispose of used batteries according to the manufacturer's instructions and your local government's recycling or disposal directives.*

### **Attention:**

*Il y a un risque d'explosion si la batterie est remplacée de façon incorrecte. Ne la remplacer qu'avec le même modèle ou équivalent recommandé par le constructeur. Recycler les batteries usées en accord avec les instructions du fabricant et les directives gouvernementales de recyclage.*





产品中有毒有害物质或元素名称及含量

AAEON System

QO4-381 Rev.A0

部件名称	有毒有害物质或元素					
	铅 (Pb)	汞 (Hg)	镉 (Cd)	六价铬 (Cr(VI))	多溴联苯 (PBB)	多溴二苯 醚(PBDE)
印刷电路板 及其电子组件	×	○	○	○	○	○
外部信号 连接器及线材	×	○	○	○	○	○
外壳	○	○	○	○	○	○
中央处理器 与内存	×	○	○	○	○	○
硬盘	×	○	○	○	○	○
液晶模块	×	×	○	○	○	○
光驱	×	○	○	○	○	○
触控模块	×	○	○	○	○	○
电源	×	○	○	○	○	○
电池	×	○	○	○	○	○

本表格依据 SJ/T 11364 的规定编制。

○：表示该有毒有害物质在该部件所有均质材料中的含量均在 GB/T 26572标准规定的限量要求以下。

×：表示该有害物质的某一均质材料超出了GB/T 26572的限量要求，然而该部件仍符合欧盟指令2011/65/EU 的规范。

备注：

一、此产品所标示之环保使用期限，系指在一般正常使用状况下。

二、上述部件物质中央处理器、内存、硬盘、光驱、电源为选购品。

三、上述部件物质液晶模块、触控模块仅一体机产品适用。

China RoHS Requirement (EN)

Hazardous and Toxic Materials List

AAEON System

QO4-381 Rev.A0

Component Name	Hazardous or Toxic Materials or Elements					
	Lead (Pb)	Mercury (Hg)	Cadmium (Cd)	Hexavalent Chromium (Cr(VI))	Polybrominated biphenyls (PBBs)	Polybrominated diphenyl ethers (PBDEs)
PCB and Components	X	O	O	O	O	O
Wires & Connectors for Ext.Connections	X	O	O	O	O	O
Chassis	O	O	O	O	O	O
CPU & RAM	X	O	O	O	O	O
HDD Drive	X	O	O	O	O	O
LCD Module	X	X	O	O	O	O
Optical Drive	X	O	O	O	O	O
Touch Control Module	X	O	O	O	O	O
PSU	X	O	O	O	O	O
Battery	X	O	O	O	O	O
<p>This form is prepared in compliance with the provisions of SJ/T 11364.</p> <p>O: The level of toxic or hazardous materials present in this component and its parts is below the limit specified by GB/T 26572.</p> <p>X: The level of toxic of hazardous materials present in the component exceed the limits specified by GB/T 26572, but is still in compliance with EU Directive 2011/65/EU (RoHS 2).</p> <p>Notes:</p> <p>1. The Environment Friendly Use Period indicated by labelling on this product is applicable only to use under normal conditions.</p> <p>2. Individual components including the CPU, RAM/memory, HDD, optical drive, and PSU are optional.</p> <p>3. LCD Module and Touch Control Module only applies to certain products which feature these components.</p>						

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# Chapter 1

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## Product Specifications

## 1.1 Specifications

### System

AI Accelerator	NVIDIA® Jetson Nano™
CPU	Quad Core ARM® Cortex®-A57 MPCore Processor
System Memory	4GB LPDDR4
Storage Device	32GB microSD (A version) or 16GB eMMC (B version)
Display Interface	HDMI 2.0
Ethernet	10/100/1000Base-TX x 1
I/O	USB3.2 Gen 1 x 4 LAN x 1 RS-232 x 2 HDMI x 1 MicroSD x 1 DC Power Input x 1 Recovery Button x 1 Micro-USB for Flash OS x 1
Expansion	M.2 E-Key 2230 x 1 (for Wi-Fi)
Indicator	Power LED x 1
OS Support	Linux (AAEON ACLinux 4.9) Linux (NVIDIA Jetpack 4.5)

### Power Supply

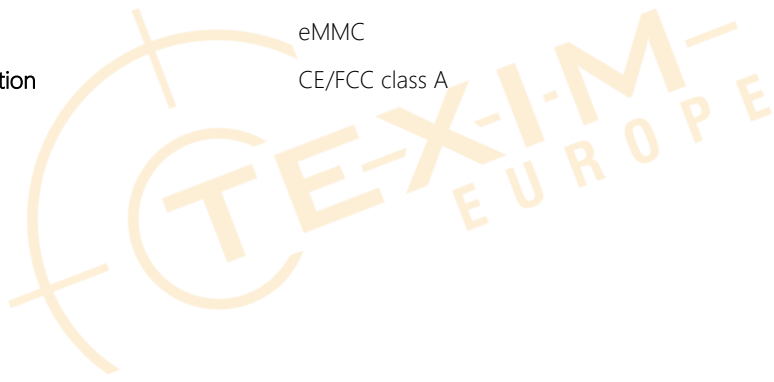
Power Requirement	12Vdc w/ 2-pin terminal block
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Mechanical

Mounting	Wallmount
Dimensions (W x D x H)	3.46" x 2.95" x 1.53" (88 mm x 75 mm x 39 mm)
Gross Weight	1.10 lbs. (0.5 kg)
Net Weight	0.66 lbs. (0.3 kg)

Environmental

Operating Temperature	-4°F ~ 122°F (-20°C ~ 50°C, according to IEC60068-2 with 0.5 m/s airflow)
Storage Temperature	-49°F ~176°F (-45°C ~ 80°C)
Storage Humidity	95% @ 40°C, non-condensing
Anti-Vibration	3 Grms/ 5 ~ 500Hz/ operation – microSD or eMMC
Certification	CE/FCC class A



## 1.2 Product Notice

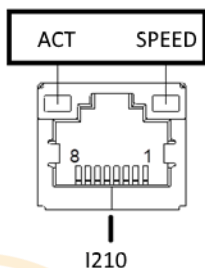
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**Micro-USB:** Micro-USB port is ideally for flashing image only.

**USB ports:** USB ports do not support USB DVD ROM because of file system.

**USB 3.2 Gen 1:** USB 3.2 Gen 1 is the current name for 5Gbps specification, formerly USB 3.0.

### LAN Indicator Behavior



TEXIM-  
EUROPE



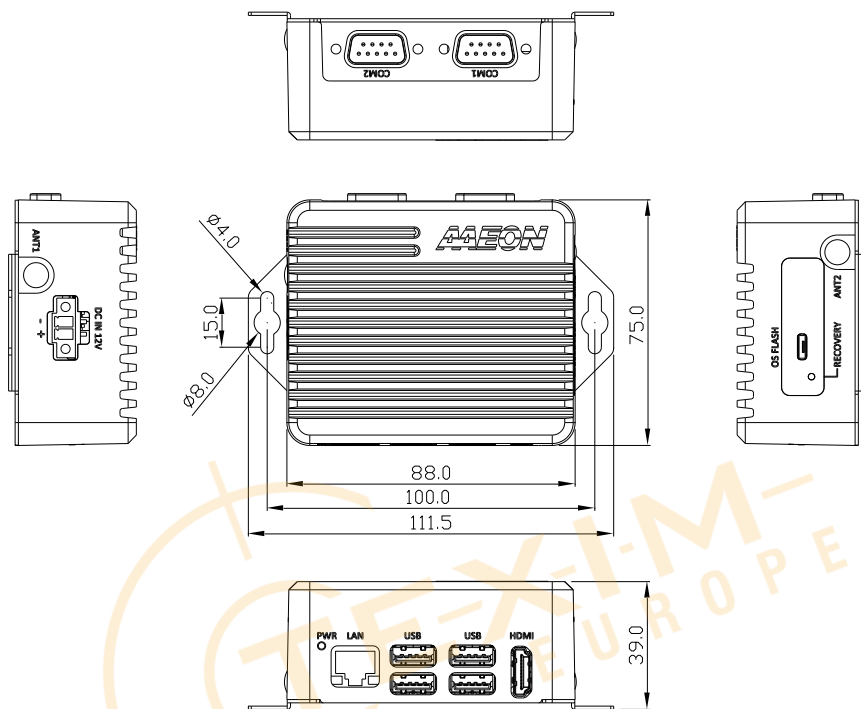
# Chapter 2

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Hardware Information

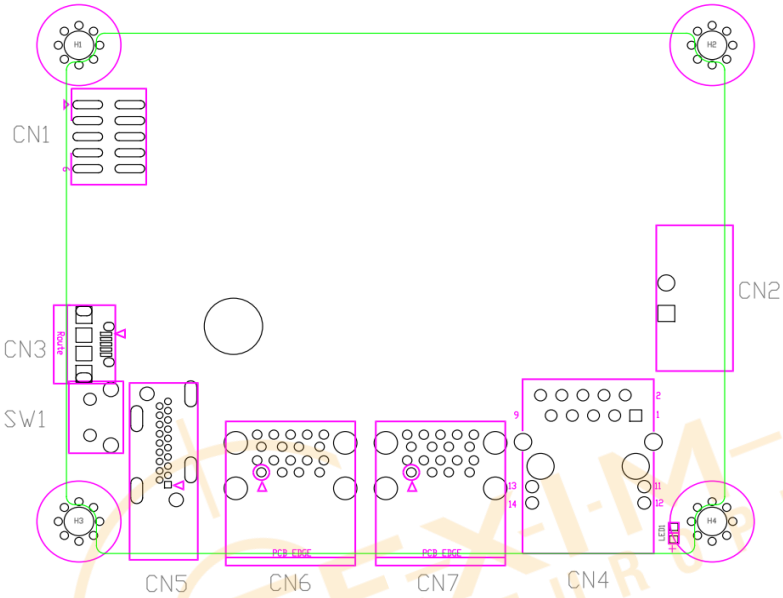


## 2.1 Dimensions

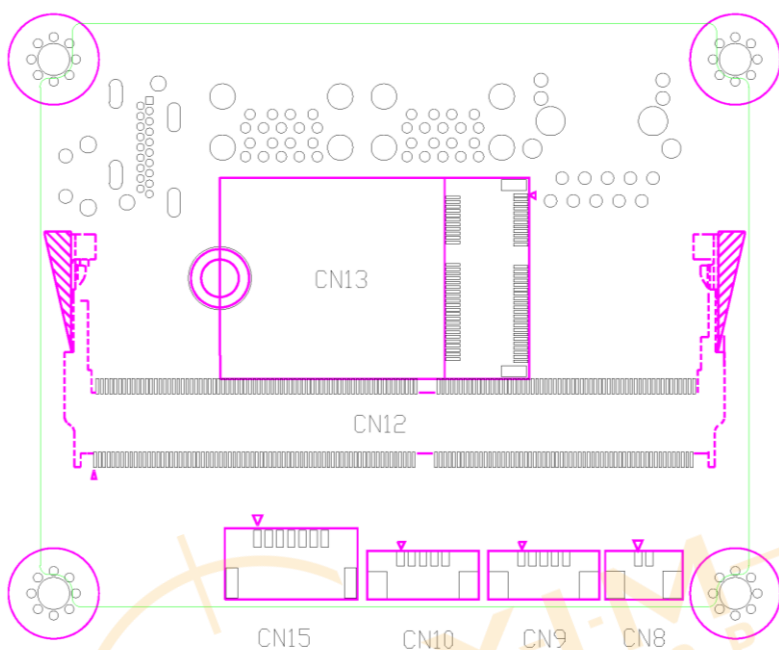


## 2.2 Jumpers and connectors

### Component Side



## Module Side



## 2.3 List of Jumpers

The board has a number of jumpers that allow you to configure your system to suit your application.

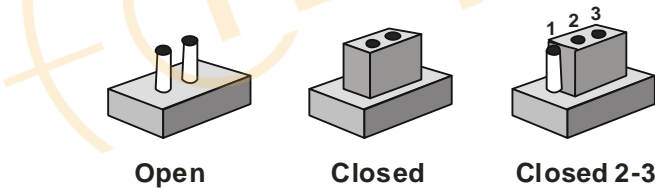
The table below shows the function of each of the board's jumpers

Label	Function
CN1 (Pin 7-8)	AT/ATX mode select

### 2.3.1 Setting Jumpers

You can configure your system to match the needs of your application by setting jumpers. A jumper is the simplest kind of electric switch. It consists of two metal pins and a small metal clip (often protected by a plastic cover) that slides over the pins to connect them. To “close” a jumper you connect the pins with the clip.

To “open” a jumper you remove the clip. Sometimes a jumper will have three pins, labeled 1, 2 and 3. In this case you would connect either pins 1 and 2 or 2 and 3.



A pair of needle-nose pliers may be helpful when working with jumpers.

If you have any questions about the best hardware configuration for your application, contact your local distributor or sales representative before you make any changes.

Generally, you simply need a standard cable to make most connections.

### 2.3.2 AT/ATX Mode Select (CN1 Pins 7-8)

The AT/ATX Mode Select functions by connecting pins 7 and 8 of CN1. To prevent damage to the system, do not connect pins 7 and 8 to any other pin.



Open – AT Mode  
(Default)



Closed – ATX Mode

CN1 pins 7-8	Function
7-8 Open	AT Power Mode (Default)
7-8 Closed	ATX Power Mode

## 2.4 List of Connectors

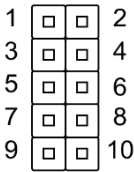
The board has a number of connectors that allow you to configure your system to suit your application.

The table below shows the function of each of the board's connectors

Label	Function
CN1	Front Panel Connector
CN2	DC Power In connector
CN3	Micro USB for Flash image
CN4	Giga LAN Connector
CN5	HDMI Connector
CN6	Dual USB 3.2 Gen 1 Connector
CN7	Dual USB 3.2 Gen 1 Connector
CN8	RTC Connector
CN9	COM1 Connector /dev/ttyTHS1
CN10	COM2 Connector /dev/ttyTHS2
CN12	Jetson NANO CPU module connector
CN13	M.2 E key
CN15	UART for Debug
SW1	Recovery switch

**Note:** USB 3.2 Gen 1 uses the same specifications as USB 3.0 (transfer rate 5Gbs).

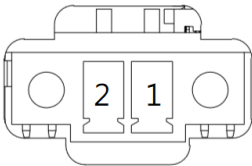
2.4.1 Front Panel Connector (CN1)



Pin	Signal	Pin	Signal
1	Button power	2	GND
3	Recovery	4	GND
5	Reset	6	GND
7	Latch set	8	Latch set
9	PWR LED	10	+5V

**Note:** Pin 7 and 8 are used for setting AT/ATX Power Mode. See [Chapter 2.3.2](#) for information. To prevent damage to your system, do not connect Pins 7 and 8 with any other pin.

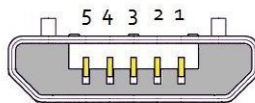
2.4.2 DC Power In Connector (CN2)



Pin	Signal	Pin	Signal
1	PWR_IN	2	GND



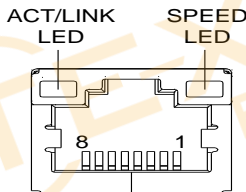
2.4.3 USB 2.0 Connector for Flash Image (CN3)



USB Micro-B

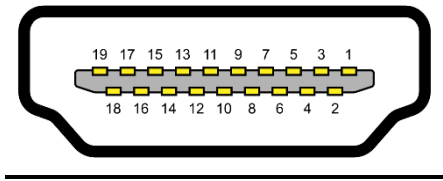
Pin	Signal	Pin	Signal
1		2	USB1-
3	USB1+	4	
5	GND		

2.4.4 LAN RJ45 Port (CN4)



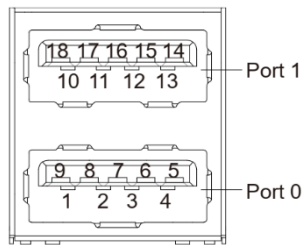
Pin	Signal	Pin	Signal
1	MDI0+	2	MDI0-
3	MDI1+	4	MDI1-
5	MDI2+	6	MDI2-
7	MDI3+	8	MDI3-

### 2.4.5 HDMI Connector (CN5)



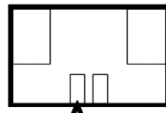
Pin	Signal	Pin	Signal
1	HDMI_DATA2_P	2	GND
3	HDMI_DATA2_N	4	HDMI_DATA1_P
5	GND	6	HDMI_DATA1_N
7	HDMI_DATA0_P	8	GND
9	HDMI_DATA0_N	10	HDMI_CLK_P
11	GND	12	HDMI_CLK_N
13	NC	14	NC
15	HDMI_SCL	16	HDMI_SDA
17	GND	18	HDMI_PWR
19	HDMI_HDP		

### 2.4.6 Dual USB 3.2 Gen 1 Connector (CN6/CN7)



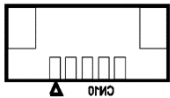
Pin	Signal	Pin	Signal
U1	VBUS_1	U10	VBUS_2
U2	(A)D-	U11	(B)D-
U3	(A)D+	U12	(B)D+
U4	GND	U13	GND
U5	(A)SSRX-	U14	(B)SSRX-
U6	(A)SSRX+	U15	(B)SSRX+
U7	GND	U16	GND
U8	(A)SSTX-	U17	(B)SSTX-
U9	(A)SSTX+	U18	(B)SSTX+

### 2.4.7 RTC Battery Connector (CN8)



Pin	Signal	Pin	Signal
1	+3V	2	GND

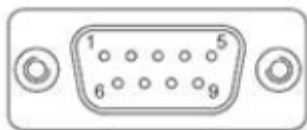
### 2.4.8 COM Port Connector (CN9/CN10)



Pin	RS-232	UART (3.3V)
1	TXD	
2	RXD	
3		UART TXD
4		UART RXD
5	GND	
6		
7		
8		
9		

Label	System Reference
COM1	/dev/ttyTHS1
COM2	/dev/ttyTHS2

## 2.4.9 COM Port Connector (System)



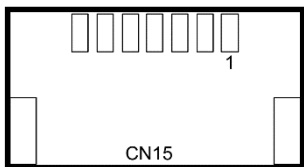
Pin	RS-232	UART (3.3V)
1		
2	RXD	
3	TXD	
4		
5	GND	
6		
7		UART RXD
8		UART TXD
9		

## 2.4.10 Jetson Nano CPU Module Connector (CN12)

Signal Name	Pin # Top Odd	Pin # Bottom Even	Signal Name
GND	1	2	GND
CS1 D0 N	3	4	CS10 D0 N
CS1 D0 P	5	6	CS10 D0 P
GND	7	8	GND
RSVD	9	10	CS10 CLK N
RSVD	11	12	CS10 CLK P
GND	13	14	GND
CS1 D1 N	15	16	CS10 D1 N
CS1 D1 P	17	18	CS10 D1 P
GND	19	20	GND
CS3 D0 N	21	22	CS12 D0 N
CS3 D0 P	23	24	CS12 D0 P
GND	25	26	GND
CS3 CLK N	27	28	CS12 CLK N
CS3 CLK P	29	30	CS12 CLK P
GND	31	32	GND
CS3 D1 N	33	34	CS12 D1 N
CS3 D1 P	35	36	CS12 D1 P
GND	37	38	GND
DP0 TXD0 N	39	40	CS14 D2 N
DP0 TXD0 P	41	42	CS14 D2 P
GND	43	44	GND
DP0 TXD1 N	45	46	CS14 D0 N
DP0 TXD1 P	47	48	CS14 D0 P
GND	49	50	GND
DP0 TXD2 N	51	52	CS14 CLK N
DP0 TXD2 P	53	54	CS14 CLK P
GND	55	56	GND
DP0 TXD3 N	57	58	CS14 D1 N
DP0 TXD3 P	59	60	CS14 D1 P
GND	61	62	GND
DP1 TXD0 N	63	64	CS14 D3 N
DP1 TXD0 P	65	66	CS14 D3 P
GND	67	68	GND
DP1 TXD1 N	69	70	DS1 D0 N
DP1 TXD1 P	71	72	DS1 D0 P
GND	73	74	GND
DP1 TXD2 N	75	76	DS1 CLK N
DP1 TXD2 P	77	78	DS1 CLK P
GND	79	80	GND
DP1 TXD3 N	81	82	DS1 D1 N
DP1 TXD3 P	83	84	DS1 D1 P
GND	85	86	GND
GPIO0	87	88	DP0 HPD
SP10 MOSI	89	90	DP0 AUX N
SP10 SCK	91	92	DP0 AUX P
SP10 MISO	93	94	HDMI CEC
SP10 CS0*	95	96	DP1 HPD
SP10 CS1*	97	98	DP1 AUX N
UART0 TXD	99	100	DP1 AUX P
UART0 RXD	101	102	GND
UART0 RTS*	103	104	SP11 MOSI
UART0 CTS*	105	106	SP11 SCK
GND	107	108	SP11 MISO
USB0 D N	109	110	SP11 CS0*
USB0 D P	111	112	SP11 CS1*
GND	113	114	CAM0 PWDN
USB1 D N	115	116	CAM0 MCLK
USB1 D P	117	118	GPIO01
GND	119	120	CAM1 PWDN
USB2 D N	121	122	CAM1 MCLK
USB2 D P	123	124	GPIO02
GND	125	126	GPIO03
GPIO04	127	128	GPIO05
GND	129	130	GPIO06
PCIED RX0 N	131	132	GND

Signal Name	Pin # Top Odd	Pin # Bottom Even	Signal Name
PCIED RX0 P	133	134	PCIED TX0 N
GND	135	136	PCIED TX0 P
PCIED RX1 N	137	138	GND
PCIED RX1 P	139	140	PCIED TX1 N
GND	141	142	PCIED TX1 P
RSVD	143	144	GND
KEY	145	146	KEY
RSVD	147	148	GND
GND	149	150	PCIED TX2 N
PCIED RX2 N	151	152	PCIED TX2 P
PCIED RX2 P	153	154	GND
GND	155	156	PCIED TX3 N
PCIED RX3 N	157	158	PCIED TX3 P
PCIED RX3 P	159	160	GND
GND	161	162	PCIED CLK N
USBSS RX N	163	164	PCIED CLK P
USBSS RX P	165	166	GND
GND	167	168	USBSS TX N
RSVD	169	170	USBSS TX P
RSVD	171	172	GND
RSVD	173	174	RSVD
RSVD	175	176	GND
GND	177	178	MOD SLEEP*
PCIE WAKE*	179	180	PCIED CLKREQ*
PCIED RST*	181	182	RSVD
RSVD	183	184	GRE MDIO N
IC20 SCL	185	186	GRE MDIO P
IC20 SDA	187	188	GRE LED LINK
IC21 SCL	189	190	GRE MDIO N
IC21 SDA	191	192	GRE MDIO P
IC20 DOUT	193	194	GRE LED ACT
IC20 DIN	195	196	GRE MDIO N
IC20 FS	197	198	GRE MDIO P
IC20 SCLK	199	200	GND
GND	201	202	GRE MDIO N
UART1 TXD	203	204	GRE MDIO P
UART1 RXD	205	206	GPIO07
UART1 RTS*	207	208	GPIO08
UART1 CTS*	209	210	CLK 3K OUT
GPIO09	211	212	GPIO10
CAM I2C SCL	213	214	FORCE RECOVERY*
CAM I2C SDA	215	216	GPIO11
GND	217	218	GPIO12
SDMMC DAT0	219	220	IC21 DOUT
SDMMC DAT1	221	222	IC21 DIN
SDMMC DAT2	223	224	IC21 FS
SDMMC DAT3	225	226	IC21 SCLK
SDMMC CMD	227	228	GPIO13
SDMMC CLK	229	230	GPIO14
GND	231	232	IC22 SCL
SHUTDOWN REQ*	233	234	IC22 SDA
PMIC BBAT	235	236	UART2 TXD
POWER EN	237	238	UART2 RXD
SYS RESET*	239	240	SLEEPWAKE*
GND	241	242	GND
GND	243	244	GND
GND	245	246	GND
GND	247	248	GND
GND	249	250	GND
VDD IN	251	252	VDD IN
VDD IN	253	254	VDD IN
VDD IN	255	256	VDD IN
VDD IN	257	258	VDD IN
VDD IN	259	260	VDD IN

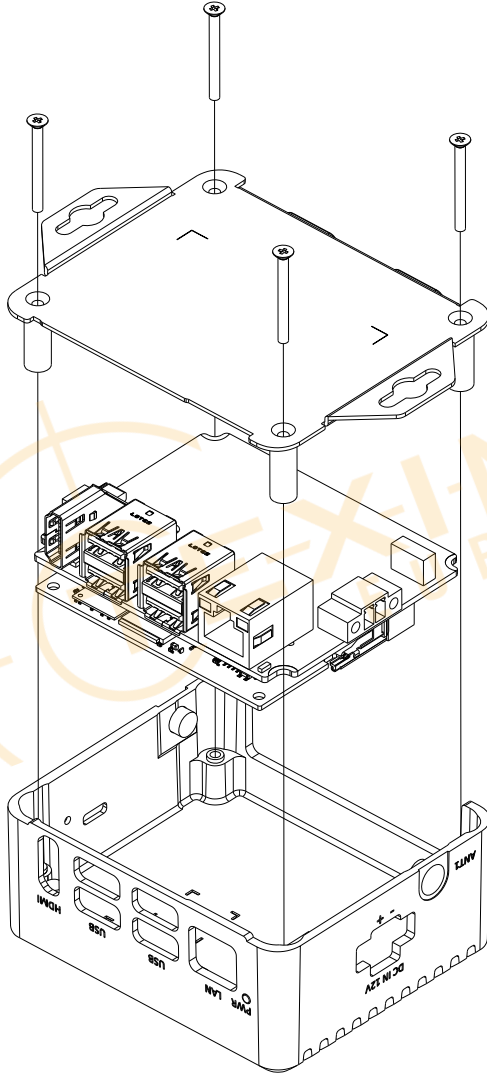
## 2.4.11 UART Debug Port Connector (CN15)



Pin	
1	3.3V
2	UART0 TXD
3	UART0 RXD
4	GND
5	I2C SCL
6	I2C SDA
7	GND

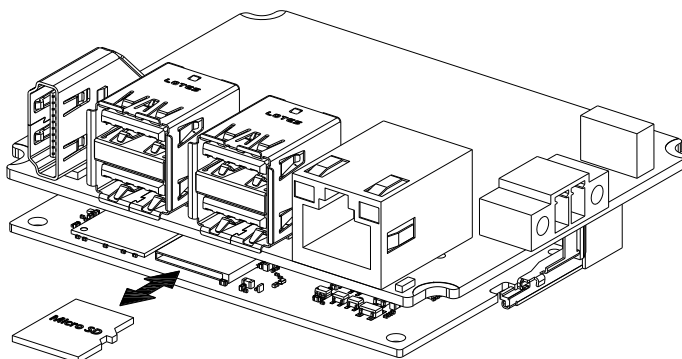
## 2.5 Hardware Assembly

### Chassis Assembly





## Micro-SD Installation



Micro-SD card installs directly onto NVIDIA Jetson Nano module. Check diagram for correct orientation before inserting card.

## M.2 Module Installation

M.2 module attaches to the BOXER-8221AI board. NVIDIA Jetson Nano module must be removed prior to installing M.2 module.



# Chapter 3

---

OS Flash guide



### 3.1 Introduction

---

This chapter details the steps to flash the Linux operating system to your BOXER-8221AI system with NVIDIA Jetson Nano. The instructions are divided into two parts depending 1) the NVIDIA JetPack version included with your Linux OS image and 2) whether your Jetson Nano has onboard eMMC storage or SD Card slot.

Jetson Nano module with SD Card slot (no onboard eMMC):

Linux OS with JetPack version prior to 4.5 **[Flash to SD Card](#)**

Linux OS with JetPack versions 4.5 and later **[Flash to System](#)**

Jetson Nano module with onboard eMMC (no SD Card slot):

All versions of JetPack **[Flash to System](#)**

If you are unsure which Jetson Nano module you have, check Ch 3.1.1 Verifying Your Jetson Nano Module.

If you are unsure which image to use, visit the AAEON support page or contact your AAEON representative.

#### Download the OS Image

Download the OS image from the product page at AAEON.com by clicking the link:

<https://www.aaeon.com/en/p/nvidia-jetson-nano-embedded-box-pc-boxer-8221ai>

### Caution: Do Not Update via Terminal

When flashing a Linux operating system, it is common practice to use the commands **sudo apt-get update** and **sudo apt-get upgrade** to ensure you have the latest version available. DO NOT USE THESE COMMANDS with your BOXER-8221AI system.

The images provided on AAEON's website include drivers and software which allows the NVIDIA SoC to recognize the various hardware features of the BOXER-8221AI. Attempting to update via terminal can erase this software and cause your system to be unable to recognize peripherals or I/O ports.

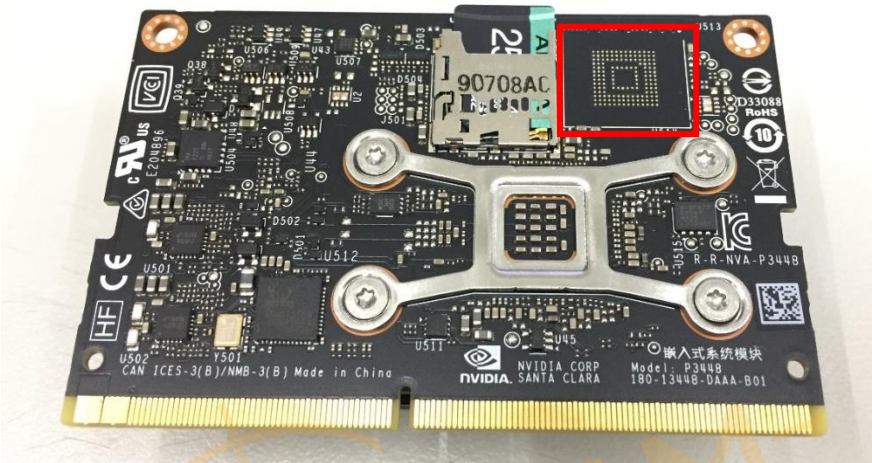
To ensure you have the latest OS image, visit the product page at the link above regularly.

### Security Notice WARNING:

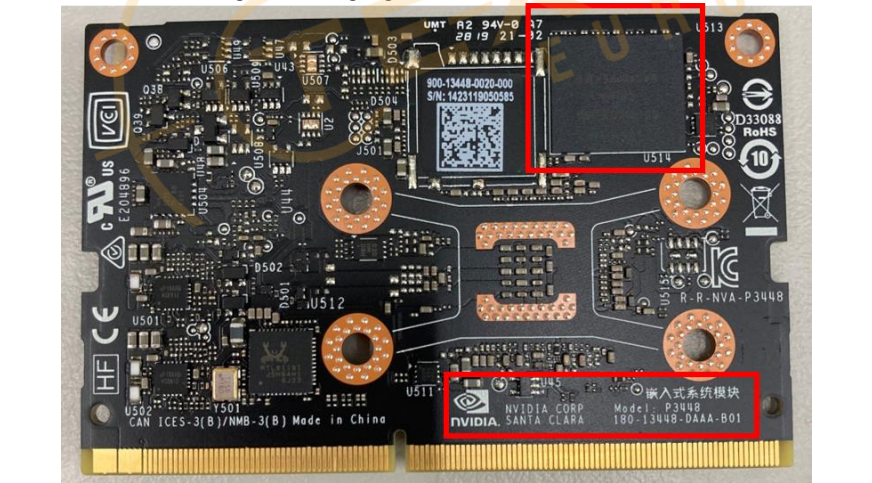
Using an image with Boot from External Storage function may carry a security risk, i.e. SD Card or SSD. AAEON cannot guarantee that devices other than eMMC as boot media are able to maintain complete security and scalability, even if Secure Boot is enabled.

### 3.1.1 Verifying Your Jetson Nano Module

If you are unsure which storage type your Jetson Nano module uses, you can perform a quick visual inspection to see if it has eMMC memory or an SD Card slot.



Jetson Nano module with SD Card slot. You can see the SD Card slot easily, as well as the lack of eMMC storage in the highlighted area.



Jetson Nano module with eMMC storage. Note the eMMC module in the highlighted square as well as the missing SD Card slot next to it.

## 3.2 Flash to microSD Card

---

This section details the steps to flashing the Linux OS image to a microSD Card for your BOXER-8221AI NVIDIA Jetson Nano system.

**Note:** This section is only applicable to installing images with JetPack versions prior to 4.5 onto Jetson Nano modules with onboard microSD Card slot (no eMMC). Read the previous section to determine if this is applicable to your system.

The steps outlined apply to ACLinux build 3 or later. To identify the build number, check the file name of the download. It should be formatted as follows, with {BN} being the build number.

**ACLinux\_4.9\_ACLNX49D.NV03.BOXER-8221AI.{BN}.tar.gz**

For example, build number 4 will be named as:

**ACLinux\_4.9\_ACLNX49D.NV03.BOXER-8221AI.4.tar.gz**

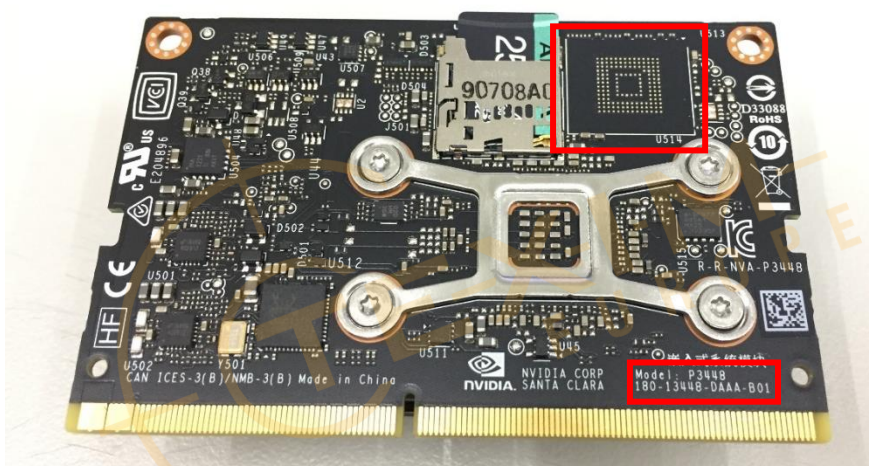
If you have any questions or are unsure which build number you have, or need help installing an older build, please contact AAEON support or ask your AAEON representative for assistance.

### 3.2.1 Before You Begin

Before beginning the process ensure you have the following:

- ACLinux Image Build 3 or later
- One host PC with operating system Ubuntu 16.04 or 18.04
- microSD Card 16GB or larger
- microSD Card USB adapter/reader (if host PC does not have a microSD Slot)
- Jetson Nano Development Kit B01 module (no onboard eMMC storage); see

image below for reference



AAEON recommends downloading balenaEtcher for the image flash process. You can download Etcher from the balena website: <https://www.balena.io/etcher/>

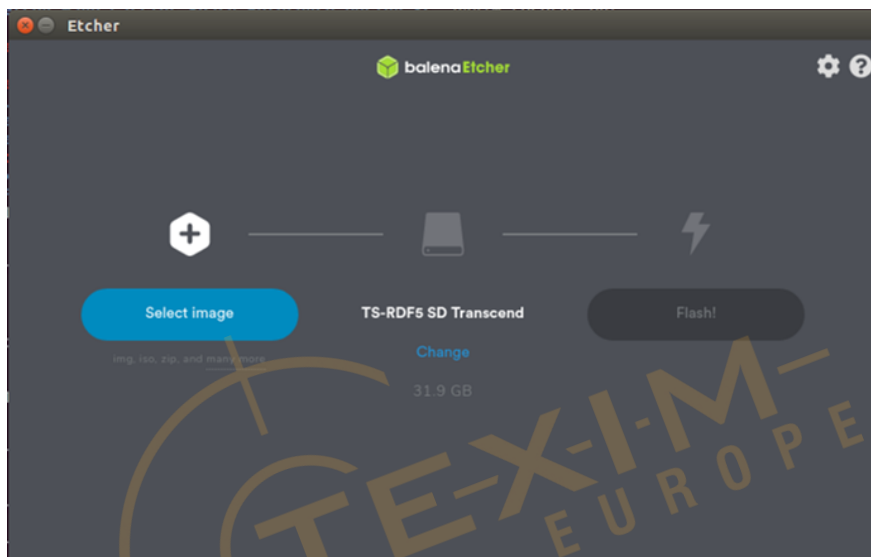
Finally, before starting, on the Linux host PC, extract the image file you downloaded using the following command in terminal (remember to replace {BN} with the actual build number in the file name):

```
$ tar xzf ACLinux_4.9_ACLNX49D.NV03.BOXER-8221AI.{BN}.tar.gz
```

### 3.2.3 Flash Image to microSD Card

**Step 1:** Insert the microSD card you want to flash into the host PC.

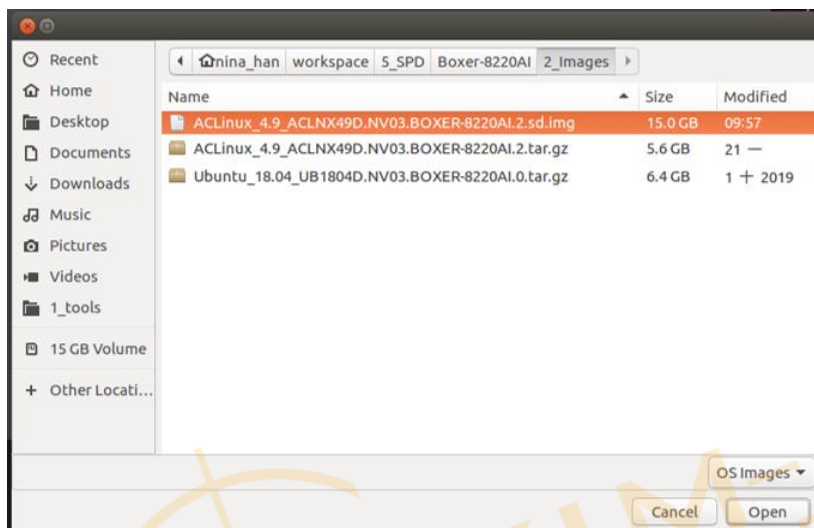
**Step 2:** Run the Etcher flash tool.



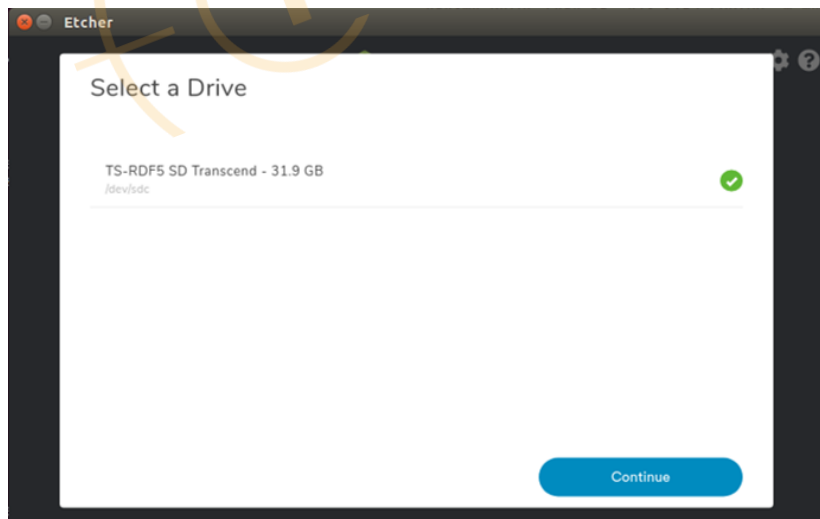


**Step 3:** Click “Select image” and choose the image file you extracted. File name should look like:

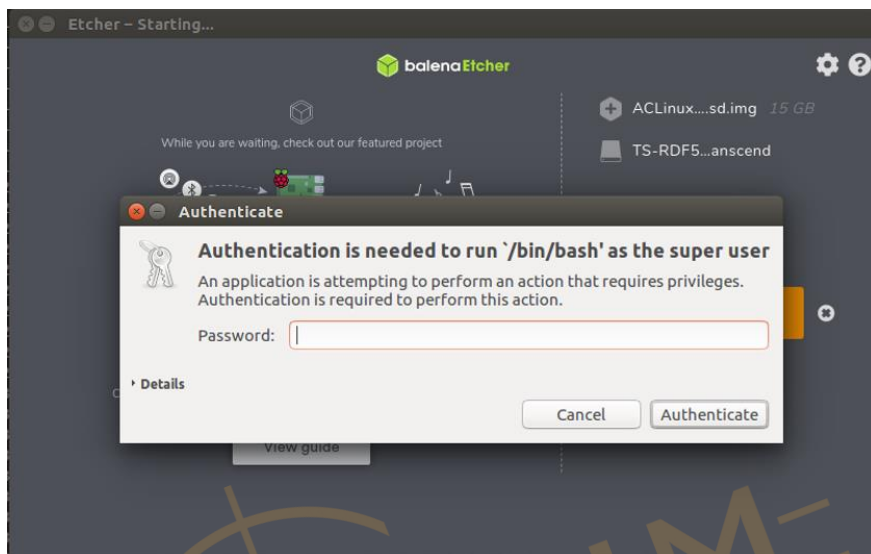
**ACLlinux\_4.9\_ACLNX49D.NV03.BOXER-8221AI.{BN}.sd.img**



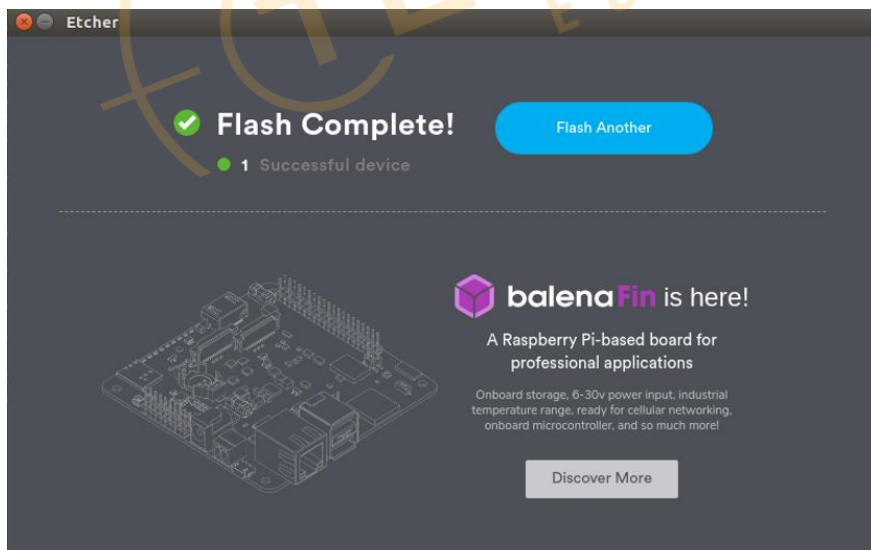
**Step 4:** Etcher will automatically choose a USB device to write to. Click “Change” to select the correct device if Etcher has not defaulted to the SD Card.



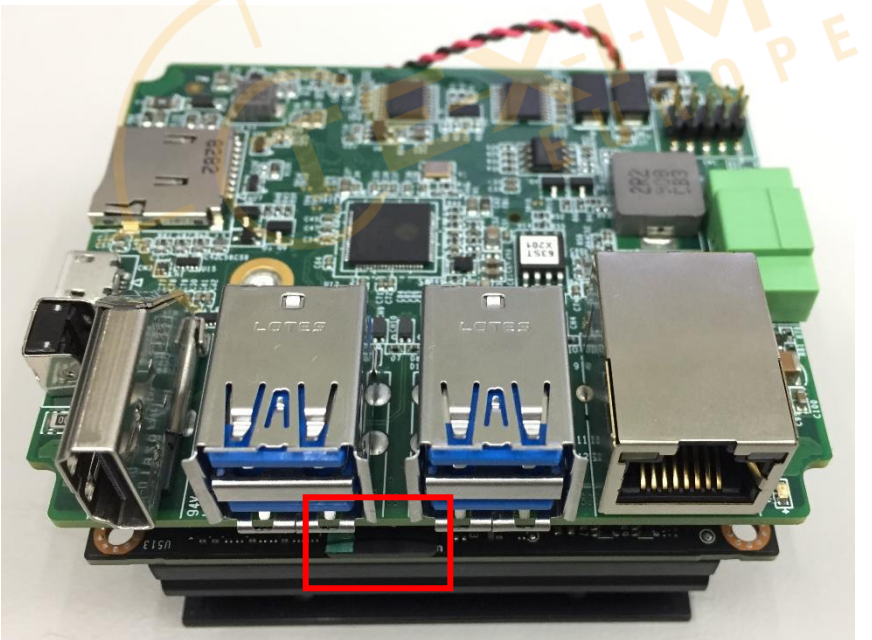
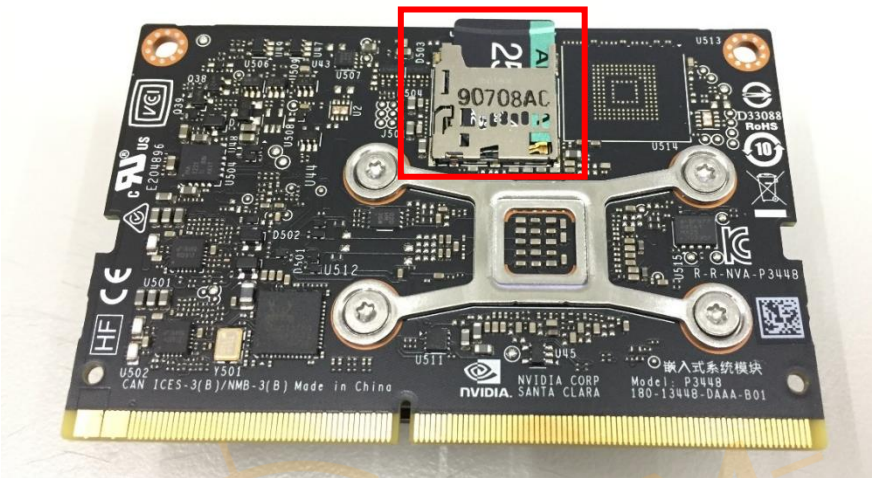
**Step 5:** Click "Flash!" to flash image to your SD Card. Ubuntu may ask for a password to continue the operation. Enter your password to continue.



**Step 6:** Wait for Etcher to complete the process.



**Step 7:** After Etcher successfully finishes, remove the microSD Card from the host PC, insert the microSD card into the NVIDIA Jetson Nano SOC, then insert the Jetson Nano SOC into the BOXER-8221AI board if you have not already done so.



### 3.3 Flash to System

---

This section details the steps to flashing the Linux OS to your BOXER-8221AI system.

**Note:** This section is applicable to the following two installation types:

For Jetson Nano modules with eMMC storage and all versions of NVIDIA JetPack

For Jetson Nano modules with microSD storage and NVIDIA JetPack 4.5 or later

If you are using a Jetson Nano module with microSD storage and wish to install an OS image with a version of JetPack prior to 4.5, see the previous section, Ch 3.2 Flash to microSD Card.

If you have any questions or are unsure which Linux OS image you should download, or need help with installation, please contact AAEON support or ask your AAEON representative for assistance.

#### 3.3.1 Before Installation

---

Before beginning the process ensure you have the following:

- One host PC with operating system Ubuntu 16.04 or 18.04
- Operating System image downloaded to host computer
- USB Cable with at least one Micro USB connector
- For Jetson Nano modules without eMMC storage, insert a microSD Card with a capacity 16MB or greater.

Make sure the NVIDIA Jetson Nano module is installed onto the BOXER-8221AI carrier board/ system, and the system is turned off and power disconnected.

Download the compressed OS image file. The file name will follow the format of:

**ACL**inux\_4.9\_**{OS\_IF}**.**{PLF\_IF}**.**{PJ\_IF}**.**{BN}**.tar.gz

For example:

**ACL**inux\_4.9\_**ACLNX49D**.**NV03**.**BOXER-8221AI**.**5**.tar.gz

*Note: Filename may differ from this example.*

- I. **{OS\_IF}** is OS Information.
- II. **{PLF\_IF}** is Platform Information; e.g. **NV03** for Jetson Nano
- III. **{PJ\_IF}** is Project Information; e.g. **BOXER-8221AI**
- IV. **{BN}** is Build Number; e.g. 0, 1, 2, etc.



### 3.3.2 Connecting to PC/ Force Recovery Mode

On Host Computer, open Linux terminal and enter the following command to extract compressed OS image files (*file name may vary*):

```
$ tar -zxvf ACLinux_4.9_ACLNX49D.NV03.BOXER-8221AI.5.tar.gz
```

Next, perform the following steps to force the system to start in USB Recovery Mode:

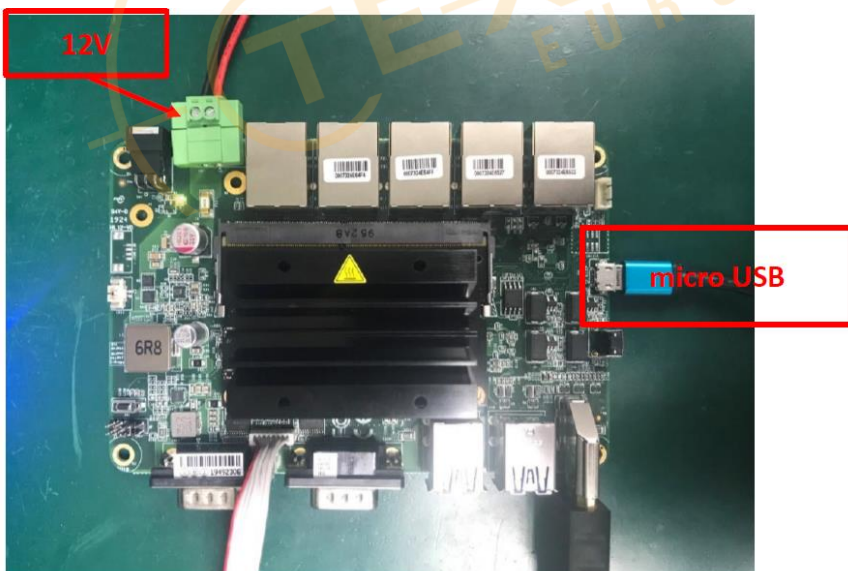
1. Connect the Micro-USB plug on the USB cable to the Recovery Port on the BOXER-8221AI and the other end to an available USB port on the host PC.
2. Connect the BOXER-8221AI power supply.
3. Press and hold the recovery key button. While holding the recovery key button, power on the system, and continue to hold the recovery key button for two seconds, then release. The BOXER-8221AI should enter recovery mode.

You can use `lsusb` command on host PC to check if the device is in recovery mode:

```
$ lsusb | grep 0955:7f21
```

You should see the following return if device is in recovery mode:

```
0955:7f21 Nvidia Corp
```



### 3.3.3 Flash Image to Board

Use the following steps to flash the OS to the BOXER-8221AI.

1. Open terminal on Ubuntu host PC, then access the bootloader folder you extracted in the previous section.
2. Enter the following command in terminal to flash the image:

```
$ sudo ./flashall.sh
```

3. Wait as the image is installed. Once finished you should see the following:

```
1.7289 Sending bcis
1.7373 tegrarcn --download bct P3448_A00_4GB_Micron_4GB_lpddr4_204Mhz_P987.bct
1.7427 Applat version 00.01.0000
1.7639 Sending bct
1.7650 [.....] 100%
1.9759
1.9762 Sending bootloader and pre-requisite binaries
1.9848 tegrarcn --download ebt cbboot.bin 0 0 --download rp1 tegra210-p3448-0000-p3449-0000-a02.dtb 0
1.9897 Applat version 00.01.0000
2.0126 Sending ebt
2.0173 [.....] 100%
2.1653 Sending rp1
2.1673 [.....] 100%
2.2013
2.2090 tegrarcn --boot recovery
2.2162 Applat version 00.01.0000
2.2465
2.2467 Retrieving storage information
2.2526 tegrarcn --oem platformdetails storage storage_info.bin
2.2626 Applat is not running on device. Continue with Bootloader
3.3943
3.4003 tegradevflash --oem platformdetails storage storage_info.bin
3.4093 Cboot version 00.01.0000
3.4151 Saved platform info in storage_info.bin
3.4237
3.4245 Flashing the device
3.4339 tegradevflash --pt flash.xml.bin --storageinfo storage_info.bin --create
3.4397 Cboot version 00.01.0000
3.4453 Writing partition GPT with gpt.bin
3.4485 [.....] 100%
3.4582 Writing partition MWC with nvboot.bin.encrypt
21.1359 [.....] 100%
21.1478 Writing partition PT with flash.xml.bin
31.4071 [.....] 100%
31.4118 Writing partition VER with qspi_bootblob_ver.txt
31.6668 [.....] 100%
31.6807 Writing partition APP with system.img
31.9519 [.....] 100%
1358.2431 Writing partition TBC with nvboot_cpu.bin.encrypt
1366.3357 [.....] 100%
1366.3485 Writing partition RP1 with tegra210-p3448-0000-p3449-0000-a02.dtb.encrypt
1366.3918 [.....] 100%
1366.4219 Writing partition EBT with cbboot.bin.encrypt
1366.4759 [.....] 100%
1366.5147 Writing partition WBO with warmboot.bin.encrypt
1366.7052 [.....] 100%
1366.7088 Writing partition BPF with sc7entry-firmware.bin.encrypt
1366.7488 [.....] 100%
1366.7587 Writing partition TOS with tos-mon-only.img.encrypt
1366.7947 [.....] 100%
1366.8119 Writing partition DTB with tegra210-p3448-0000-p3449-0000-a02.dtb.encrypt
1366.8546 [.....] 100%
1366.8644 Writing partition LNX with boot.img.encrypt
1366.9316 [.....] 100%
1366.9756 Writing partition EKS partition magic header mismatch!
1367.0848 Writing partition EKS with eks.img
1367.0892 [.....] 100%
1367.0927 Writing partition BMP with bmp.blob
1367.1349 [.....] 100%
1367.1487 Writing partition RP4 with rp4.blob
1367.1917 [.....] 100%
1367.2571
1367.2652 tegradevflash --write BCT P3448_A00_4GB_Micron_4GB_lpddr4_204Mhz_P987.bct
1367.2749 Cboot version 00.01.0000
1367.2778 Writing partition BCT with P3448_A00_4GB_Micron_4GB_lpddr4_204Mhz_P987.bct
1367.2857 [.....] 100%
1373.9389
1373.9392 Flashing completed
```





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